

Data: Thursday, October 25, 2018.

RECAP

- Strict vs. weak stationarity
- Mean function $\mu(t) = E[Y_t]$
- Covariance function $\gamma(t, t+h) = \text{Cov}(Y_t, Y_{t+h})$

For a (weak) stationary time series, the covariance function simplifies to:

$\gamma(h)$ does not depend on t .

This function is specifically referred to as an **autocovariance function**.

In this context, we define the **autocorrelation function** to be

$$\begin{aligned}\rho(h) &= \text{Corr}(Y_t, Y_{t+h}), \\ &= \frac{\text{Cov}(Y_t, Y_{t+h})}{\sqrt{\text{Var}(Y_t) \text{Var}(Y_{t+h})}}, \\ &= \frac{\text{Cov}(Y_t, Y_{t+h})}{\sqrt{\text{Cov}(Y_t, Y_t)} \sqrt{\text{Cov}(Y_{t+h}, Y_{t+h})}}, \\ &= \frac{\gamma(h)}{\gamma(0)}.\end{aligned}$$

PROPERTIES:

1. $\gamma(0) \geq 0 \Leftrightarrow \text{Var}[Y_t] \geq 0$
2. $|\gamma(h)| \leq \gamma(0) \Leftrightarrow \frac{|\gamma(h)|}{\gamma(0)} = |\rho(h)| \leq 1$
3. $\gamma(h) = \gamma(-h)$, $\rho(h) = \rho(-h)$
Even functions

$\text{Corr}(Y_2, Y_5) = \text{Corr}(Y_5, Y_2)$
→ We usually want to forecast to the future


Recall that for MA(1) model

$$\gamma(h) = \begin{cases} \sigma^2(1+\theta^2) & \text{if } h=0 \\ \sigma^2\theta & \text{if } h=\pm 1 \\ 0 & \text{otherwise} \end{cases}$$

Noting that $\gamma(0) = \sigma^2(1+\theta^2)$

$$\rho(h) = \begin{cases} 1 & \text{if } h=0 \\ \frac{\theta}{1+\theta^2} & \text{if } h=\pm 1 \\ 0 & \text{otherwise} \end{cases}$$

You would expect a spike at 1

By looking at an ACF plot, that behaves like that, you could  modeling with MA(1).

Example:

First order autoregression AR(1)

A times series $\{y_t\} \sim \text{AR}(1)$ behaves according to the following relationship:

$$y_t = \phi y_{t-1} + \varepsilon_t$$

where $|\phi| < 1$ and $\{\varepsilon_t\} \sim \text{WN}(0, \sigma^2)$

(?) and ε_t and y_s are uncorrelated for $s < t$.

This makes
AR(1)
stationary

Derive the autocovariance function of h and autocorrelation of h . ($\gamma(h)$ and $\rho(h)$).

$$\begin{aligned} \bullet \quad \mathbb{E}[y_t] &= \mathbb{E}[\phi y_{t-1} + \varepsilon_t] \\ &= \phi \mathbb{E}[y_{t-1}] + \mathbb{E}[\varepsilon_t] \end{aligned}$$

$$\therefore \mathbb{E}[y_t] = \phi \mathbb{E}[y_{t-1}]$$

$$\begin{aligned} \mu &= \phi \mu \quad \text{because } \{y_t\} \text{ is stationary} \\ \Rightarrow \mu &= 0 \end{aligned}$$

$$\therefore \mu = 0 \text{ since } \phi \neq 1.$$

$$\bullet \quad \underline{\gamma(h)} = \text{Cov}(y_t, y_{t+h})$$

$$= \mathbb{E}[y_t y_{t+h}] - \mathbb{E}[y_t] \mathbb{E}[y_{t+h}]$$

$$= \mathbb{E}[y_t (\phi y_{t+h-1} + \varepsilon_{t+h})]$$

$$= \mathbb{E}[\theta y_{t+h-1} y_t + \varepsilon_{t+h} y_t]$$

$$= \theta \mathbb{E}[y_t y_{t+h-1}] + \mathbb{E}[y_t \varepsilon_{t+h}]$$

$$= \theta \gamma(h-1)$$

$$= \theta^2 \gamma(h-2)$$

$$= \theta^3 \gamma(h-3)$$

⋮

$$= \theta^h \gamma(0)$$

$$\cdot \gamma(0) = \text{Var}(Y_t)$$

$$= \text{cov}(Y_t, Y_t)$$

$$= E[Y_t^2] - E[Y_t]^2$$

$$= E[(\phi Y_{t-1} + \varepsilon_t)^2]$$

$$= E[\phi^2 Y_{t-1}^2 + 2\phi Y_{t-1} \varepsilon_t + \varepsilon_t^2]$$

$$= \phi^2 E[Y_{t-1}^2] + 2\phi E[Y_{t-1} \varepsilon_t] + E[\varepsilon_t^2]$$

$$= \phi^2 \gamma(0) + 0 + \sigma^2$$

$$= \phi^2 \gamma(0) + \sigma^2$$

$$\Rightarrow \gamma(0) = \frac{\sigma^2}{1-\phi^2}$$

therefore, $\gamma(h) = \frac{\phi^{|h|} \sigma^2}{1-\phi^2}$ for $h \in \mathbb{Z}$.

↗ forward, backward

$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} = \frac{\gamma(h)}{\gamma(0)} = \phi^{|h|} \text{ for } h \in \mathbb{Z}.$$

Exponentially smaller as h increases.

Whereas we have calculated ACF's from specified models, typically we observe actual data and calculate sample estimates of the quantities.

Given an observed time series $\{Y_t\} = \{Y_1, Y_2, \dots, Y_n\}$

- **Mean function:**

$$\bar{Y} = \frac{1}{n} \sum_{t=1}^n Y_t = \hat{\mu}$$

- **Sample autocovariance function:**

$$\hat{\gamma}(h) = \frac{1}{n} \sum_{t=1}^{n-|h|} (Y_t - \bar{Y})(Y_{t+|h|} - \bar{Y})$$

↓
bias but required for non-regime

- **Sample autocorrelation function:**

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)}$$

The sample ACF can be used to check for "unrelatedness" in a time series. This is achieved by comparing $\hat{\rho}(h)$ values to a threshold, which, if exceeded, indicates significant correlation.



These thresholds rely on the asymptotic distribution $\tilde{\rho}(h)$.

For large n , $\tilde{\rho}(h) \sim N(0, \frac{1}{n})$

if the time series is uncorrelated.

The threshold is really a 95% confidence interval for $\rho(h)$ and is given by

$$\pm \frac{1.96}{\sqrt{n}}$$

thus $\hat{p}(h) \notin \left[-\frac{1.96}{\sqrt{n}}, \frac{1.96}{\sqrt{n}} \right]$ is indicative of significant correlation.